

# COMPUTING ATTRACTING ELLIPSOIDS FOR NONLINEAR SYSTEMS USING AN INTERVAL LYAPUNOV EQUATION

SWIM'2016

Léopold Houdin, Alexandre Goldsztejn, Gilles Chabert,  
Frédéric Boyer

Juin 2016

# Outline

## Introduction

### Context

Overall Objective

Lyapunov Functions

Concrete Objective

## Contribution

Overview

Testing a Neighborhood

Building an Ellipsoid

First Algorithm

Building a Neighborhood

Second Algorithm

## Conclusion

# Context

We consider a continuous-time dynamical system :

$$\dot{x} = f(x), \quad f : \mathbb{R}^n \rightarrow \mathbb{R}^n,$$

and an *exponentially stable* point  $x^*$ .

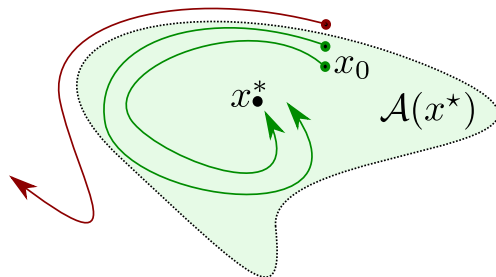
# Context

## Exponential Stability

All the trajectories starting inside a neighborhood  $\mathcal{A}(x^*)$  of  $x^*$  converge to  $x^*$  faster than an exponential decay :

$$\forall x_0 \in \mathcal{A}(x^*), \exists t_0, \forall t \geq t_0, \quad \|x(t) - x^*\| \leq \alpha \|x_0 - x^*\| e^{-\beta t}.$$

for some nonnegative constants  $\alpha, \beta$ .



# Context

Exponential stability is proven by studying the sign of the eigenvalues of  $Df(x^*)$ , the Jacobian matrix of  $f$  at the fixpoint.

# Context

Exponential stability is proven by studying the sign of the eigenvalues of  $Df(x^*)$ , the Jacobian matrix of  $f$  at the fixpoint.

➡ These eigenvalues also characterize the attraction strength ( $\beta$ ).

# Context

However, the linearization gives no information about the size of the basin of attraction

# Context

However, the linearization gives no information about the size of the basin of attraction

$f(x)$	$Df(0)$	$\mathcal{A}(0)$
$c^3 x^3 - cx$	$-c$	$(-\frac{1}{c}, \frac{1}{c})$
$\frac{x^3}{c} - cx$	$-c$	$(-c, c)$



# Outline

## Introduction

Context

**Overall Objective**

Lyapunov Functions

Concrete Objective

## Contribution

Overview

Testing a Neighborhood

Building an Ellipsoid

First Algorithm

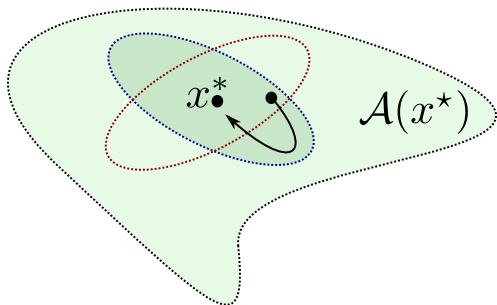
Building a Neighborhood

Second Algorithm

## Conclusion

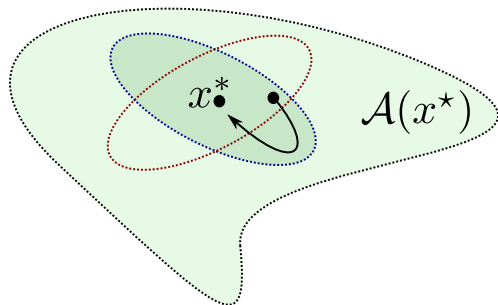
# Overall Objective

Build a subset of  $\mathcal{A}(x^*)$  in a **fast** (polynomial time) and **guaranteed** way.



# Overall Objective

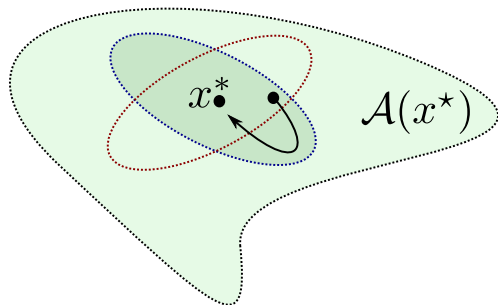
Build a subset of  $\mathcal{A}(x^*)$  in a **fast** (polynomial time) and **guaranteed** way.



The subset must also be a **positive invariant**.

# Overall Objective

Build a subset of  $\mathcal{A}(x^*)$  in a **fast** (polynomial time) and **guaranteed** way.



The subset must also be a **positive invariant**.

Our approach is based on **Lyapunov theory**.

# Outline

## Introduction

Context

Overall Objective

**Lyapunov Functions**

Concrete Objective

## Contribution

Overview

Testing a Neighborhood

Building an Ellipsoid

First Algorithm

Building a Neighborhood

Second Algorithm

## Conclusion

# Lyapunov Functions

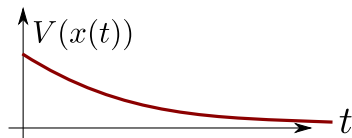
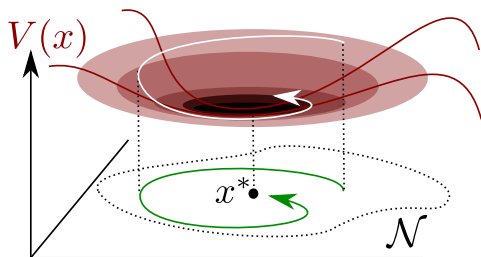
A Lyapunov function is locally an energy-like function

$V : \mathbb{R}^n \rightarrow \mathbb{R}$  such that

$$V(x^*) = 0$$

and there exists an open neighborhood  $\mathcal{N}$  of  $x^*$  such that

$$\forall x \in \mathcal{N} \setminus \{x^*\} \quad \begin{cases} V(x) > 0 \\ \dot{V}(x) < 0 \end{cases} \quad \text{with} \quad \dot{V}(x) := \frac{d}{dt} V(x(t)).$$



# Lyapunov Functions

There always exists<sup>1</sup> a Lyapunov function of the form

$$V(x) = (x - x^*)^T P (x - x^*)$$

where  $P$  is a SPD (*symmetric positive definite*) matrix.

---

1. In the case of an exponentially stable point.

# Lyapunov Functions

There always exists<sup>1</sup> a Lyapunov function of the form

$$V(x) = (x - x^*)^T P (x - x^*)$$

where  $P$  is a SPD (*symmetric positive definite*) matrix.

And we know how to build it.

---

1. In the case of an exponentially stable point.



# Lyapunov Functions

There always exists<sup>1</sup> a Lyapunov function of the form

$$V(x) = (x - x^*)^T P (x - x^*)$$

where  $P$  is a SPD (*symmetric positive definite*) matrix.

And we know how to build it.

In short,

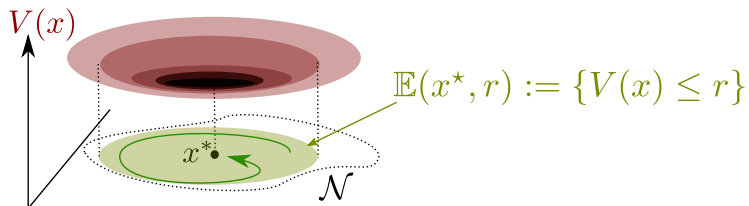
$$V(x) = \|x - x^*\|_P.$$

---

1. In the case of an exponentially stable point.

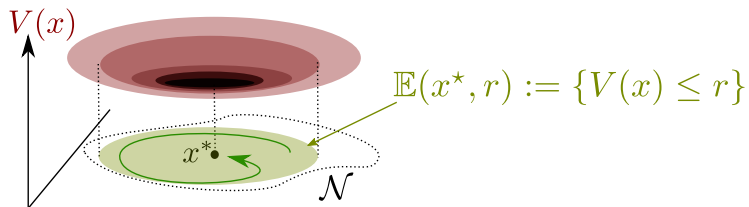
# Lyapunov Functions

Then, all the level sets of  $V$  **inside**  $\mathcal{N}$  are attracting, and even more, positive invariants.



# Lyapunov Functions

Then, all the level sets of  $V$  **inside**  $\mathcal{N}$  are attracting, and even more, positive invariants.



**Problem :** We know  $V$  but we don't know  $\mathcal{N}$ .

# Lyapunov Functions

In fact, since

$$V(x) = \|x - x^*\|_P$$

# Lyapunov Functions

In fact, since

$$V(x) = \|x - x^*\|_P$$

$$\forall x \in \mathcal{N} \setminus \{x^*\} \quad V(x) > 0 \quad \checkmark$$

# Lyapunov Functions

In fact, since

$$V(x) = \|x - x^*\|_P$$

$$\forall x \in \mathcal{N} \setminus \{x^*\} \quad V(x) > 0 \quad \checkmark$$

$$\forall x \in \mathcal{N} \setminus \{x^*\} \quad \dot{V}(x) < 0 \quad ?$$

# Lyapunov Functions

In fact, since

$$V(x) = \|x - x^*\|_P$$

$$\forall x \in \mathcal{N} \setminus \{x^*\} \quad V(x) > 0 \quad \checkmark$$

$$\forall x \in \mathcal{N} \setminus \{x^*\} \quad \dot{V}(x) < 0 \quad ?$$

Only the second property needs to be enforced.

# Lyapunov Functions

In fact, since

$$V(x) = \|x - x^*\|_P$$

$$\forall x \in \mathcal{N} \setminus \{x^*\} \quad V(x) > 0 \quad \checkmark$$

$$\forall x \in \mathcal{N} \setminus \{x^*\} \quad \dot{V}(x) < 0 \quad ?$$

Only the second property needs to be enforced.

**Note :**

$$\dot{V}(x) = \frac{d}{dt} V(x(t)) = \nabla V(x)^T f(x) = 2(x - x^*)^T P f(x)$$



# Outline

## Introduction

Context

Overall Objective

Lyapunov Functions

**Concrete Objective**

## Contribution

Overview

Testing a Neighborhood

Building an Ellipsoid

First Algorithm

Building a Neighborhood

Second Algorithm

## Conclusion

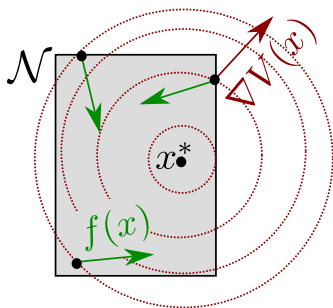
# Concrete Objective

Our goal is to

# Concrete Objective

Our goal is to

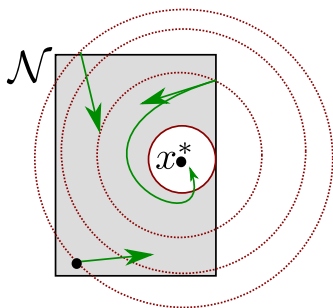
- ▶ Build a neighborhood  $\mathcal{N}$  where  $\dot{V} < 0$



# Concrete Objective

Our goal is to

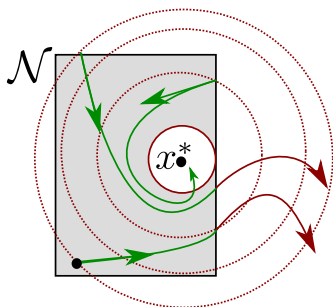
- ▶ Build a neighborhood  $\mathcal{N}$  where  $\dot{V} < 0$
- ▶ Build a  $P$ -ellipsoid inside  $\mathcal{N}$



# Concrete Objective

Our goal is to

- ▶ Build a neighborhood  $\mathcal{N}$  where  $\dot{V} < 0$
- ▶ Build a  $P$ -ellipsoid inside  $\mathcal{N}$

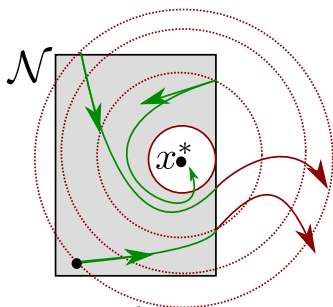


**Warning** :  $\mathcal{N}$  is not necessarily inside the basin !

# Concrete Objective

Our goal is to

- ▶ Build a neighborhood  $\mathcal{N}$  where  $\dot{V} < 0$
- ▶ Build a  $P$ -ellipsoid inside  $\mathcal{N}$



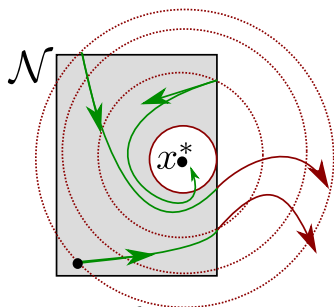
**Warning** :  $\mathcal{N}$  is not necessarily inside the basin !

... unless  $\mathcal{N}$  is a  $P$ -ellipsoid, in which case we kill two birds with one stone.

# Concrete Objective

Our goal is to

- ▶ Build a neighborhood  $\mathcal{N}$  where  $\dot{V} < 0$
- ▶ Build a  $P$ -ellipsoid inside  $\mathcal{N}$



**Warning** :  $\mathcal{N}$  is not necessarily inside the basin !

... unless  $\mathcal{N}$  is a  $P$ -ellipsoid, in which case we kill two birds with one stone.

➡ difficult with interval methods.

# Concrete Objective

## Interval approach

Set  $\mathcal{N} := [x]$  (an arbitrary box around  $x^*$ ) and prove :

$$\forall x \in [x], x \neq x^*, \quad \dot{V}(x) = (x - x^*)^T Pf(x) < 0.$$



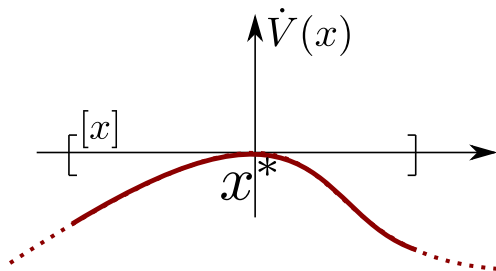
# Concrete Objective

## Interval approach

Set  $\mathcal{N} := [x]$  (an arbitrary box around  $x^*$ ) and prove :

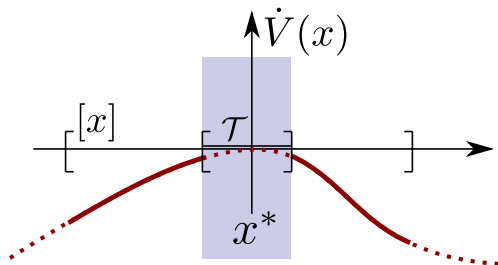
$$\forall x \in [x], x \neq x^*, \quad \dot{V}(x) = (x - x^*)^T P f(x) < 0.$$

**Problem :** naively applying interval arithmetic does not work since  $\dot{V}(x^*) = 0$ .



# Concrete Objective

Ratschan & She proposed to “remove” a small region  $\mathcal{T}$  (called *target*) around  $x^*$ .

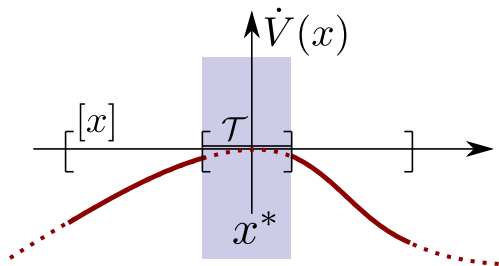


$$\text{If } \forall x \notin \mathcal{T}, \dot{V}(x) < 0,$$

all trajectories in a level set inside  $[x]$  reach the target.

# Concrete Objective

Ratschan & She proposed to “remove” a small region  $\mathcal{T}$  (called *target*) around  $x^*$ .



$$\text{If } \forall x \notin \mathcal{T}, \dot{V}(x) < 0,$$

all trajectories in a level set inside  $[x]$  reach the target.

**Problem :** convergence to  $x^*$  is not proven.

## Concrete Objective

Delanoue, Jaulin and Cottenceanu prove

$$\forall x \neq x^*, \dot{V}(x) < 0$$

by checking the concavity of  $\dot{V}$

## Concrete Objective

Delanoue, Jaulin and Cottenceanu prove

$$\forall x \neq x^*, \dot{V}(x) < 0$$

by checking the concavity of  $\dot{V}$ , i.e., by checking

$$\forall x \in [x], \quad D^2 \dot{V}(x) \text{ is ND (negative definite).}$$

# Concrete Objective

Delanoue, Jaulin and Cottenceanu prove

$$\forall x \neq x^*, \dot{V}(x) < 0$$

by checking the concavity of  $\dot{V}$ , i.e., by checking

$$\forall x \in [x], \quad D^2 \dot{V}(x) \text{ is ND (negative definite).}$$

➡ Uncertainty on  $x^*$  can easily be taken into account with a “thick” function

$$\dot{V} : x \mapsto (x - [x^*])^T Pf(x)$$

# Concrete Objective

Delanoue, Jaulin and Cottenceanu prove

$$\forall x \neq x^*, \dot{V}(x) < 0$$

by checking the concavity of  $\dot{V}$ , i.e., by checking

$$\forall x \in [x], \quad D^2 \dot{V}(x) \text{ is ND (negative definite).}$$

➡ Uncertainty on  $x^*$  can easily be taken into account with a “thick” function

$$\dot{V} : x \mapsto (x - [x^*])^T Pf(x)$$

**Problem :**

# Concrete Objective

Delanoue, Jaulin and Cottenceanu prove

$$\forall x \neq x^*, \dot{V}(x) < 0$$

by checking the concavity of  $\dot{V}$ , i.e., by checking

$$\forall x \in [x], \quad D^2 \dot{V}(x) \text{ is ND (negative definite).}$$

➡ Uncertainty on  $x^*$  can easily be taken into account with a “thick” function

$$\dot{V} : x \mapsto (x - [x^*])^T Pf(x)$$

## Problem :

- ▶ Works as a test (yes/no ➡ needs heuristic)



# Concrete Objective

Delanoue, Jaulin and Cottenceanu prove

$$\forall x \neq x^*, \dot{V}(x) < 0$$

by checking the concavity of  $\dot{V}$ , i.e., by checking

$$\forall x \in [x], \quad D^2 \dot{V}(x) \text{ is ND (negative definite).}$$

➡ Uncertainty on  $x^*$  can easily be taken into account with a “thick” function

$$\dot{V} : x \mapsto (x - [x^*])^T Pf(x)$$

## Problem :

- ▶ Works as a test (yes/no ➡ needs heuristic)
- ▶ Resorts to second-order derivatives.

# Outline

## Introduction

Context

Overall Objective

Lyapunov Functions

Concrete Objective

## Contribution

### Overview

Testing a Neighborhood

Building an Ellipsoid

First Algorithm

Building a Neighborhood

Second Algorithm

## Conclusion

# Overview

## Contribution.

We propose two algorithms :

- ▶ The first also works as a test but uses only 1st order derivatives

# Overview

## Contribution.

We propose two algorithms :

- ▶ The first also works as a test but uses only 1st order derivatives
- ▶ The second uses 2nd order derivative but always gives a solution (under mild conditions)

# Overview

## Contribution.

We propose two algorithms :

- ▶ The first also works as a test but uses only 1st order derivatives
- ▶ The second uses 2nd order derivative but always gives a solution (under mild conditions)
- ▶ Both work directly with ellipsoids (inputs and outputs are radii)

# Outline

## Introduction

Context

Overall Objective

Lyapunov Functions

Concrete Objective

## Contribution

Overview

**Testing a Neighborhood**

Building an Ellipsoid

First Algorithm

Building a Neighborhood

Second Algorithm

## Conclusion

# Testing a Neighborhood

First, we know from the fundamental theorem of analysis that, for all  $x \in \mathbb{R}^n$  there exists a matrix  $S(x)$  such that

$$f(x) = f(x^*) + S(x)(x - x^*) = S(x)(x - x^*)$$

# Testing a Neighborhood

First, we know from the fundamental theorem of analysis that, for all  $x \in \mathbb{R}^n$  there exists a matrix  $S(x)$  such that

$$f(x) = f(x^*) + S(x)(x - x^*) = S(x)(x - x^*)$$

and

$$\forall [x] \in \mathbb{I}\mathbb{R}^n \quad S([x]) \subseteq Df([x]).$$



# Testing a Neighborhood

First, we know from the fundamental theorem of analysis that, for all  $x \in \mathbb{R}^n$  there exists a matrix  $S(x)$  such that

$$f(x) = f(x^*) + S(x)(x - x^*) = S(x)(x - x^*)$$

and

$$\forall [x] \in \mathbb{IR}^n \quad S([x]) \subseteq Df([x]).$$

**Proposition (“Interval Lyapunov Equation”)**

$\forall x \in [x]$ , define  $Q(x)$  as follows :

$$Q(x) := S(x)^T P + P S(x).$$

If  $Q([x])$  contains only ND matrices, then  $\mathcal{N} := [x]$  is a valid neighborhood.

# Testing a Neighborhood

**Proof :**

$$\forall x \in [x], \quad \dot{V}(x) = 2(x - x^*)^T P f(x)$$

# Testing a Neighborhood

**Proof :**

$$\begin{aligned}\forall x \in [x], \quad \dot{V}(x) &= 2(x - x^*)^T P f(x) \\ &= 2(x - x^*)^T P S(x)(x - x^*)\end{aligned}$$

# Testing a Neighborhood

**Proof :**

$$\begin{aligned}\forall x \in [x], \quad \dot{V}(x) &= 2(x - x^*)^T P f(x) \\ &= 2(x - x^*)^T P S(x)(x - x^*) \\ &= (x - x^*)^T (S(x)^T P + P S(x))(x - x^*)\end{aligned}$$

# Testing a Neighborhood

**Proof :**

$$\begin{aligned}\forall x \in [x], \quad \dot{V}(x) &= 2(x - x^*)^T P f(x) \\ &= 2(x - x^*)^T P S(x)(x - x^*) \\ &= (x - x^*)^T (S(x)^T P + P S(x))(x - x^*) \\ &\quad (\text{using } 2x^T A x = x^T (A^T + A)x)\end{aligned}$$

# Testing a Neighborhood

**Proof :**

$$\begin{aligned}\forall x \in [x], \quad \dot{V}(x) &= 2(x - x^*)^T P f(x) \\ &= 2(x - x^*)^T P S(x)(x - x^*) \\ &= (x - x^*)^T (S(x)^T P + P S(x))(x - x^*) \\ &\quad (\text{using } 2x^T A x = x^T (A^T + A)x) \\ &= (x - x^*)^T Q(x)(x - x^*)\end{aligned}$$

# Testing a Neighborhood

**Proof :**

$$\begin{aligned}\forall x \in [x], \quad \dot{V}(x) &= 2(x - x^*)^T P f(x) \\ &= 2(x - x^*)^T P S(x)(x - x^*) \\ &= (x - x^*)^T (S(x)^T P + P S(x))(x - x^*) \\ &\quad (\text{using } 2x^T A x = x^T (A^T + A)x) \\ &= (x - x^*)^T Q(x)(x - x^*)\end{aligned}$$

and since  $Q(x)$  is ND by hypothesis,  $x \neq x^* \implies \dot{V}(x) < 0$ .

# Testing a Neighborhood

Since  $P$  satisfies

$$Df(x^*)^T P + P Df(x^*) \sim -I$$



# Testing a Neighborhood

Since  $P$  satisfies

$$Df(x^*)^T P + P Df(x^*) \sim -I$$

We have

$$Q(x^*) \sim -I.$$

# Testing a Neighborhood

Since  $P$  satisfies

$$Df(x^*)^T P + P Df(x^*) \sim -I$$

We have

$$Q(x^*) \sim -I.$$

So, for sufficiently small boxes  $[x]$ , the test will succeed.

# Testing a Neighborhood

Since  $P$  satisfies

$$Df(x^*)^T P + P Df(x^*) \sim -I$$

We have

$$Q(x^*) \sim -I.$$

So, for sufficiently small boxes  $[x]$ , the test will succeed.

➡ We now have to build a  $P$ -ellipsoid inside  $[x]$ .

# Testing a Neighborhood

Since  $P$  satisfies

$$Df(x^*)^T P + P Df(x^*) \sim -I$$

We have

$$Q(x^*) \sim -I.$$

So, for sufficiently small boxes  $[x]$ , the test will succeed.

- ➡ We now have to build a  $P$ -ellipsoid inside  $[x]$ .
- ➡ And take into account the uncertainty on  $x^*$ .

# Outline

## Introduction

Context

Overall Objective

Lyapunov Functions

Concrete Objective

## Contribution

Overview

Testing a Neighborhood

**Building an Ellipsoid**

First Algorithm

Building a Neighborhood

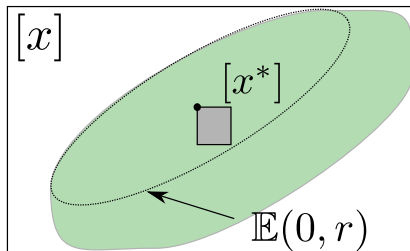
Second Algorithm

## Conclusion

# Building an Ellipsoid

So we have first to find the largest value of  $r$  such that

$$[x] \supseteq [x^*] + \square(\mathbb{E}(0, r))$$

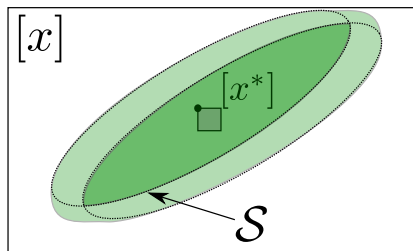


# Building an Ellipsoid

And then build the set

$$\mathcal{S} := \bigcap_{x \in [x^*]} x + \square(\mathbb{E}(0, r))$$

which is attracting.

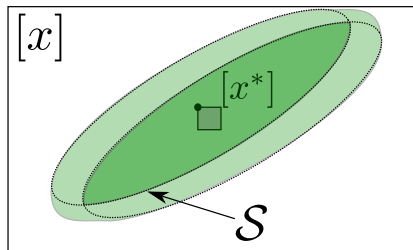


# Building an Ellipsoid

And then build the set

$$\mathcal{S} := \bigcap_{x \in [x^*]} x + \square(\mathbb{E}(0, r))$$

which is attracting.



**Note :**

- ▶  $\mathcal{S}$  may not be invariant

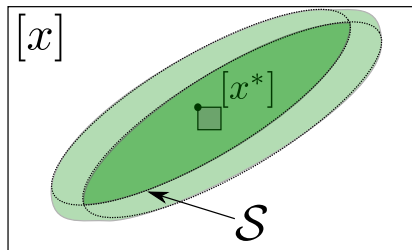


# Building an Ellipsoid

And then build the set

$$\mathcal{S} := \bigcap_{x \in [x^*]} x + \square(\mathbb{E}(0, r))$$

which is attracting.



## Note :

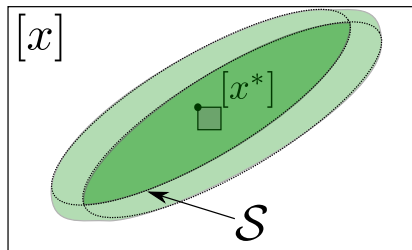
- ▶  $\mathcal{S}$  may not be invariant
- ▶  $\mathcal{S}$  may even not contain  $x^*$  !

# Building an Ellipsoid

And then build the set

$$\mathcal{S} := \bigcap_{x \in [x^*]} x + \square(\mathbb{E}(0, r))$$

which is attracting.



## Note :

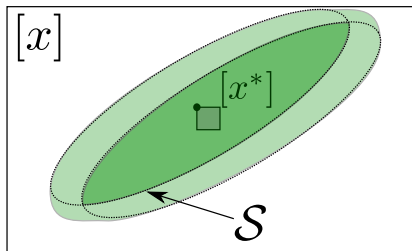
- ▶  $\mathcal{S}$  may not be invariant
- ▶  $\mathcal{S}$  may even not contain  $x^*$  !
- ▶ But will be in practice (as  $[x^*]$  is very small)

# Building an Ellipsoid

And then build the set

$$\mathcal{S} := \bigcap_{x \in [x^*]} x + \square(\mathbb{E}(0, r))$$

which is attracting.



## Note :

- ▶  $\mathcal{S}$  may not be invariant
- ▶  $\mathcal{S}$  may even not contain  $x^*$  !
- ▶ But will be in practice (as  $[x^*]$  is very small)

**Problem :**  $\mathcal{S}$  is not an ellipsoid (and difficult to compute).

# Building an Ellipsoid

**Idea :** we proceed in the other way round.

We start from a candidate ellipsoid

$$\mathbb{E}(\hat{x}, \hat{r})$$

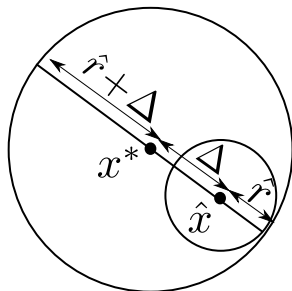
with  $\hat{x} \in [x^*]$  and build the box  $[x]$  accordingly.

# Building an Ellipsoid

Define

$$[\Delta] := \left\| [x^*] - \hat{x} \right\|_{\rho}.$$

Thanks to the triangular inequality, we have :

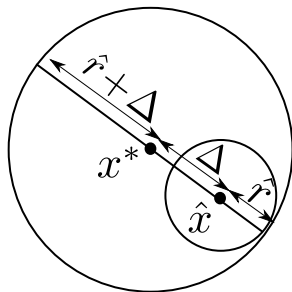


# Building an Ellipsoid

Define

$$[\Delta] := \left\| [x^*] - \hat{x} \right\|_{\rho}.$$

Thanks to the triangular inequality, we have :



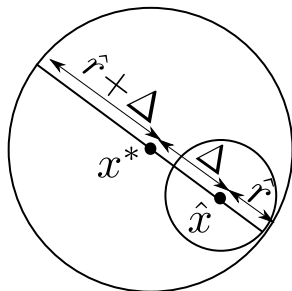
$$\blacktriangleright \mathbb{E}(\hat{x}, \hat{r}) \subseteq \mathbb{E}(x^*, \hat{r} + \overline{\Delta}).$$

# Building an Ellipsoid

Define

$$[\Delta] := \left\| [x^*] - \hat{x} \right\|_{\rho}.$$

Thanks to the triangular inequality, we have :

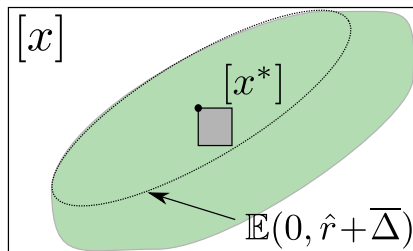


- ▶  $\mathbb{E}(\hat{x}, \hat{r}) \subseteq \mathbb{E}(x^*, \hat{r} + \bar{\Delta})$ .
- ▶ If  $\bar{\Delta} \leq \hat{r}$  then  $x^* \in \mathbb{E}(\hat{x}, \hat{r})$ .

# Building an Ellipsoid

Define

$$[x] := [x^*] + \square(\mathbb{E}(0, \hat{r} + \bar{\Delta}))$$

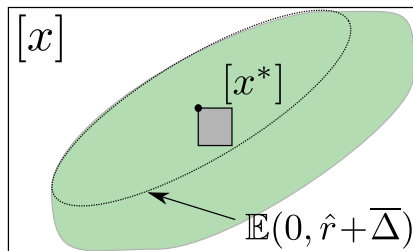




# Building an Ellipsoid

Define

$$[x] := [x^*] + \square(\mathbb{E}(0, \hat{r} + \bar{\Delta}))$$

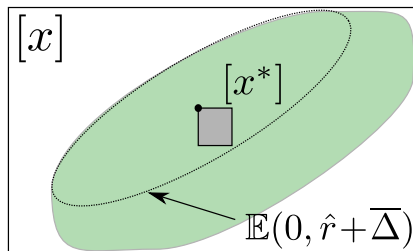


If  $Q([x])$  is ND :

# Building an Ellipsoid

Define

$$[x] := [x^*] + \square(\mathbb{E}(0, \hat{r} + \bar{\Delta}))$$



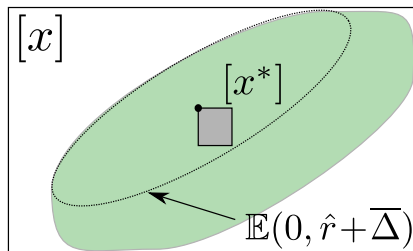
If  $Q([x])$  is ND :

$\implies [x]$  is a valid neighborhood

# Building an Ellipsoid

Define

$$[x] := [x^*] + \square(\mathbb{E}(0, \hat{r} + \bar{\Delta}))$$



If  $Q([x])$  is ND :

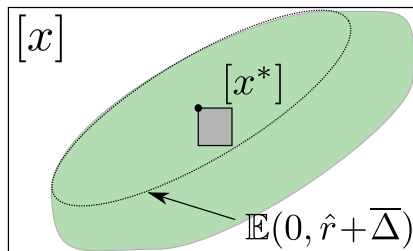
$\implies [x]$  is a valid neighborhood

$\implies E(x^*, \hat{r} + \bar{\Delta})$  is invariant

# Building an Ellipsoid

Define

$$[x] := [x^*] + \square(\mathbb{E}(0, \hat{r} + \bar{\Delta}))$$



If  $Q([x])$  is ND :

$\implies [x]$  is a valid neighborhood

$\implies E(x^*, \hat{r} + \bar{\Delta})$  is invariant

$\implies E(\hat{x}, \hat{r})$  is attracting

# Outline

## Introduction

Context

Overall Objective

Lyapunov Functions

Concrete Objective

## Contribution

Overview

Testing a Neighborhood

Building an Ellipsoid

**First Algorithm**

Building a Neighborhood

Second Algorithm

## Conclusion

# First Algorithm

## Summary

$$\bar{\Delta} \geq \left\| [x^*] - \hat{x} \right\|_P,$$

# First Algorithm

## Summary

$$\bar{\Delta} \geq \left\| [x^*] - \hat{x} \right\|_P,$$

$$[x] \supseteq [x^*] + \square(\mathbb{E}(\mathbf{0}, \hat{r} + \bar{\Delta})),$$

# First Algorithm

## Summary

$$\bar{\Delta} \geq \left\| [x^*] - \hat{x} \right\|_P,$$

$$[x] \supseteq [x^*] + \square(\mathbb{E}(\mathbf{0}, \hat{r} + \bar{\Delta})),$$

$$[J] \supseteq [Df]([x]),$$



# First Algorithm

## Summary

$$\bar{\Delta} \geq \left\| [x^*] - \hat{x} \right\|_P,$$

$$[x] \supseteq [x^*] + \square(\mathbb{E}(\mathbf{0}, \hat{r} + \bar{\Delta})),$$

$$[J] \supseteq [Df]([x]),$$

$$[Q] \supseteq [J]^T P + P[J].$$

# First Algorithm

## Summary

$$\bar{\Delta} \geq \left\| [x^*] - \hat{x} \right\|_P,$$

$$[x] \supseteq [x^*] + \square(\mathbb{E}(0, \hat{r} + \bar{\Delta})),$$

$$[J] \supseteq [Df]([x]),$$

$$[Q] \supseteq [J]^T P + P[J].$$

If  $[Q]$  is ND and  $\bar{\Delta} \leq \hat{r}$  then

# First Algorithm

## Summary

$$\bar{\Delta} \geq \left\| [x^*] - \hat{x} \right\|_P,$$

$$[x] \supseteq [x^*] + \square(\mathbb{E}(\mathbf{0}, \hat{r} + \bar{\Delta})),$$

$$[J] \supseteq [Df]([x]),$$

$$[Q] \supseteq [J]^T P + P[J].$$

If  $[Q]$  is ND and  $\bar{\Delta} \leq \hat{r}$  then

$$x^* \in \mathbb{E}(\hat{x}, \hat{r}) \subseteq \mathbb{E}(x^*, \hat{r} + \bar{\Delta}) \subseteq \mathcal{A}(x^*).$$

# Outline

## Introduction

Context

Overall Objective

Lyapunov Functions

Concrete Objective

## Contribution

Overview

Testing a Neighborhood

Building an Ellipsoid

First Algorithm

**Building a Neighborhood**

Second Algorithm

## Conclusion

## Building a Neighborhood

We want to build a domain  $\mathcal{N}$  around  $x^*$  where the matrix function  $Q(x) = S(x)^T P + PS(x)$  is ND.

## Building a Neighborhood

We want to build a domain  $\mathcal{N}$  around  $x^*$  where the matrix function  $Q(x) = S(x)^T P + PS(x)$  is ND.

Since  $Q(x^*) \sim -I$ , we replace the condition

$$Q(x) \text{ ND}$$

by the sufficient condition

$$\|Q(x) + I\| < 1.$$

## Building a Neighborhood

We want to build a domain  $\mathcal{N}$  around  $x^*$  where the matrix function  $Q(x) = S(x)^T P + PS(x)$  is ND.

Since  $Q(x^*) \sim -I$ , we replace the condition

$$Q(x) \text{ ND}$$

by the sufficient condition

$$\|Q(x) + I\| < 1.$$

We can then *linearize* this relation to obtain a condition

$$\|x - \hat{x}\|_P \leq \dots$$

## Building a Neighborhood

We want to build a domain  $\mathcal{N}$  around  $x^*$  where the matrix function  $Q(x) = S(x)^T P + PS(x)$  is ND.

Since  $Q(x^*) \sim -I$ , we replace the condition

$$Q(x) \text{ ND}$$

by the sufficient condition

$$\|Q(x) + I\| < 1.$$

We can then *linearize* this relation to obtain a condition

$$\|x - \hat{x}\|_P \leq \dots$$

using bounds  $L$  and  $L'$  on the  $P$ -norm Lipschitz constants of  $S$  and  $S^T$ , on an initial arbitrary box  $[x]$ .



# Building a Neighborhood

The constants in the equivalence relation between the  $\infty$ -norm and  $P$ -norm involve the two extremal eigenvalues  $\underline{\lambda}$  and  $\overline{\lambda}$  of  $P$ .

# Building a Neighborhood

The constants in the equivalence relation between the  $\infty$ -norm and  $P$ -norm involve the two extremal eigenvalues  $\underline{\lambda}$  and  $\bar{\lambda}$  of  $P$ .

➡ We need an algorithm for rigorously bounding eigenvalues (e.g. interval variant of Gerschgorin's circles)

# Outline

## Introduction

Context

Overall Objective

Lyapunov Functions

Concrete Objective

## Contribution

Overview

Testing a Neighborhood

Building an Ellipsoid

First Algorithm

Building a Neighborhood

**Second Algorithm**

## Conclusion

# Second Algorithm

## Summary

$$\bar{\Delta} \geq \left\| [x^*] - \hat{x} \right\|_P,$$

# Second Algorithm

## Summary

$$\bar{\Delta} \geq \left\| [x^*] - \hat{x} \right\|_P,$$

$$\nu \geq \sqrt{\frac{n\bar{\lambda}}{\underline{\lambda}}} \left\| [Q^*] + I \right\|_{\infty} \quad \text{with} \quad \begin{cases} [Q^*] \supseteq [J^*]^T P + P [J^*] \\ [J^*] \supseteq [Df]([x^*]) \end{cases}$$

# Second Algorithm

## Summary

$$\bar{\Delta} \geq \left\| [x^*] - \hat{x} \right\|_P,$$

$$\nu \geq \sqrt{\frac{n\bar{\lambda}}{\underline{\lambda}}} \left\| [Q^*] + I \right\|_{\infty} \quad \text{with} \quad \begin{cases} [Q^*] \supseteq [J^*]^T P + P [J^*] \\ [J^*] \supseteq [Df]([x^*]) \end{cases}$$

$$[x] \supseteq [x^*] + \square\left(\mathbb{E}(0, \hat{r} + \bar{\Delta})\right),$$

# Second Algorithm

## Summary

$$\bar{\Delta} \geq \left\| [x^*] - \hat{x} \right\|_P,$$

$$\nu \geq \sqrt{\frac{n\bar{\lambda}}{\underline{\lambda}}} \left\| [Q^*] + I \right\|_{\infty} \quad \text{with} \quad \begin{cases} [Q^*] \supseteq [J^*]^T P + P [J^*] \\ [J^*] \supseteq [Df]([x^*]) \end{cases}$$

$$[x] \supseteq [x^*] + \square\left(\mathbb{E}(0, \hat{r} + \bar{\Delta})\right),$$

$$\check{r} := \frac{1 - \nu}{(L + L') \bar{\lambda}} - \bar{\Delta}.$$

# Second Algorithm

## Summary

$$\bar{\Delta} \geq \left\| [x^*] - \hat{x} \right\|_P,$$

$$\nu \geq \sqrt{\frac{n\bar{\lambda}}{\underline{\lambda}}} \left\| [Q^*] + I \right\|_{\infty} \quad \text{with} \quad \begin{cases} [Q^*] \supseteq [J^*]^T P + P [J^*] \\ [J^*] \supseteq [Df]([x^*]) \end{cases}$$

$$[x] \supseteq [x^*] + \square(\mathbb{E}(0, \hat{r} + \bar{\Delta})),$$

$$\check{r} := \frac{1 - \nu}{(L + L') \bar{\lambda}} - \bar{\Delta}.$$

If  $\nu < 1$  and  $\min\{\hat{r}, \check{r}\} \geq \bar{\Delta}$  then



# Second Algorithm

## Summary

$$\bar{\Delta} \geq \left\| [x^*] - \hat{x} \right\|_P,$$

$$\nu \geq \sqrt{\frac{n\bar{\lambda}}{\underline{\lambda}}} \left\| [Q^*] + I \right\|_{\infty} \quad \text{with} \quad \begin{cases} [Q^*] \supseteq [J^*]^T P + P [J^*] \\ [J^*] \supseteq [Df]([x^*]) \end{cases}$$

$$[x] \supseteq [x^*] + \square(\mathbb{E}(0, \hat{r} + \bar{\Delta})),$$

$$\check{r} := \frac{1 - \nu}{(L + L') \bar{\lambda}} - \bar{\Delta}.$$

If  $\nu < 1$  and  $\min\{\hat{r}, \check{r}\} \geq \bar{\Delta}$  then

$$x^* \in \mathbb{E}(\hat{x}, \min\{\hat{r}, \check{r}\}) \subseteq \mathcal{A}(x^*).$$

# Conclusion

# Conclusion

- ▶ We can build a certified attraction region around a fixpoint

# Conclusion

- ▶ We can build a certified attraction region around a fixpoint
- + Even if the fixpoint is approximately known

# Conclusion

- ▶ We can build a certified attraction region around a fixpoint
- + Even if the fixpoint is approximately known
- + Only first-order derivative are necessary

# Conclusion

- ▶ We can build a certified attraction region around a fixpoint
- + Even if the fixpoint is approximately known
- + Only first-order derivative are necessary
- + Experiments show that the size of the region is large compared to existing approaches (see research report)

# Conclusion

- ▶ We can build a certified attraction region around a fixpoint
- + Even if the fixpoint is approximately known
- + Only first-order derivative are necessary
- + Experiments show that the size of the region is large compared to existing approaches (see research report)
- + The algorithm scales up

# Conclusion

- ▶ We can build a certified attraction region around a fixpoint
- + Even if the fixpoint is approximately known
- + Only first-order derivative are necessary
- + Experiments show that the size of the region is large compared to existing approaches (see research report)
- + The algorithm scales up
- Invariance is lost in theory (but not in practice)



Thanks !

## Algebraic approach

Assume  $f$  is polynomial. Fix  $r > 0$ .

## Algebraic approach

Assume  $f$  is polynomial. Fix  $r > 0$ .

If there exists a polynomial  $p(x)$  such that

$$\forall x \in \mathbb{R}^n, \quad p(x) \geq 0 \quad \wedge \quad -\underbrace{(x - x^*)^T P f(x)}_{\dot{V}(x)} + p(x)(V(x) - r) \geq 0$$

then  $\mathbb{E}(x^*, r)$  is a correct answer.

## Algebraic approach

Assume  $f$  is polynomial. Fix  $r > 0$ .

If there exists a polynomial  $p(x)$  such that

$$\forall x \in \mathbb{R}^n, \quad p(x) \geq 0 \quad \wedge \quad -\underbrace{(x - x^*)^T P f(x)}_{\dot{V}(x)} + p(x)(V(x) - r) \geq 0$$

then  $\mathbb{E}(x^*, r)$  is a correct answer.

➡ Tractable with LMI solver if we impose *sum of square decomposition* in place of  $\geq 0$ .

## Algebraic approach

Assume  $f$  is polynomial. Fix  $r > 0$ .

If there exists a polynomial  $p(x)$  such that

$$\forall x \in \mathbb{R}^n, \quad p(x) \geq 0 \quad \wedge \quad - \underbrace{(x - x^*)^T Pf(x)}_{\dot{V}(x)} + p(x)(V(x) - r) \geq 0$$

then  $\mathbb{E}(x^*, r)$  is a correct answer.

➡ Tractable with LMI solver if we impose *sum of square decomposition* in place of  $\geq 0$ .

### Problem :

- ▶ Polynomiality assumption

## Algebraic approach

Assume  $f$  is polynomial. Fix  $r > 0$ .

If there exists a polynomial  $p(x)$  such that

$$\forall x \in \mathbb{R}^n, \quad p(x) \geq 0 \quad \wedge \quad - \underbrace{(x - x^*)^T P f(x)}_{\dot{V}(x)} + p(x) (V(x) - r) \geq 0$$

then  $\mathbb{E}(x^*, r)$  is a correct answer.

➡ Tractable with LMI solver if we impose *sum of square decomposition* in place of  $\geq 0$ .

### Problem :

- ▶ Polynomiality assumption
- ▶ LMI solver not robust with respect to rounding errors

## Algebraic approach

Assume  $f$  is polynomial. Fix  $r > 0$ .

If there exists a polynomial  $p(x)$  such that

$$\forall x \in \mathbb{R}^n, \quad p(x) \geq 0 \quad \wedge \quad - \underbrace{(x - x^*)^T P f(x)}_{\dot{V}(x)} + p(x) (V(x) - r) \geq 0$$

then  $\mathbb{E}(x^*, r)$  is a correct answer.

➡ Tractable with LMI solver if we impose *sum of square decomposition* in place of  $\geq 0$ .

### Problem :

- ▶ Polynomiality assumption
- ▶ LMI solver not robust with respect to rounding errors
- ▶ Cannot handle uncertainty on  $x^*$  ( $x^* \in [x^*]$ )

Let us consider first a simpler case of  $q : \mathbb{R} \rightarrow \mathbb{R}$ .



Let us consider first a simpler case of  $q : \mathbb{R} \rightarrow \mathbb{R}$ .  
Assume that we have :

Let us consider first a simpler case of  $q : \mathbb{R} \rightarrow \mathbb{R}$ .

Assume that we have :

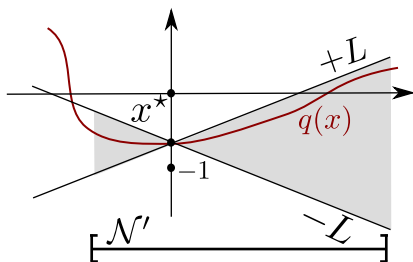
- ▶ a point  $x^*$  s.t.  $q(x^*) \sim -1$

Let us consider first a simpler case of  $q : \mathbb{R} \rightarrow \mathbb{R}$ .

Assume that we have :

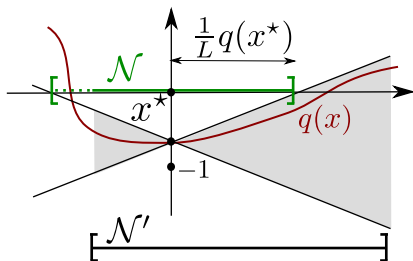
- ▶ a point  $x^*$  s.t.  $q(x^*) \sim -1$
- ▶ a Lipschitz bound  $L$  on  $q$  over an (arbitrary initial) set  $\mathcal{N}'$  :

$$\forall x, y \in \mathcal{N}' \quad \|q(x) - q(y)\| \leq L\|x - y\|.$$



Then

$$\left( x \in \mathcal{N}' \wedge \|x - x^*\| < \frac{1}{L}q(x^*) \right) \implies q(x) < 0$$



## Generalization

$$Q(x) = S(x)^T P + PS(x)$$

## Generalization

$$Q(x) = S(x)^T P + PS(x)$$

We need Lipschitz constants for  $S$  and  $S^T$  on an initial domain

$$\mathcal{N}' := \|x - \hat{x}\| \leq \hat{r}$$

## Generalization

$$Q(x) = S(x)^T P + PS(x)$$

We need Lipschitz constants for  $S$  and  $S^T$  on an initial domain

$$\mathcal{N}' := \|x - \hat{x}\| \leq \hat{r}$$

and a bound  $\nu$  on  $\|Q(x^*) + I\|$ . Then :

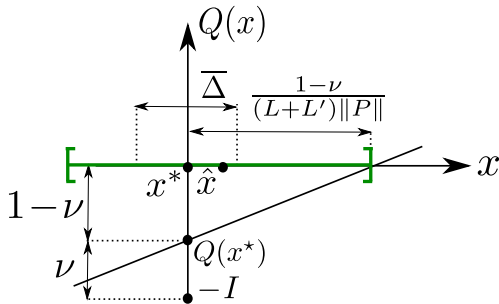
## Generalization

$$Q(x) = S(x)^T P + PS(x)$$

We need Lipschitz constants for  $S$  and  $S^T$  on an initial domain

$$\mathcal{N}' := \|x - \hat{x}\| \leq \hat{r}$$

and a bound  $\nu$  on  $\|Q(x^*) + I\|$ . Then :





The neighborhood is therefore characterized by :

$$\|x - \hat{x}\| \leq \min(\check{r}, \hat{r})$$

with

$$\check{r} := \frac{1 - \nu}{(L + L') \bar{\lambda}} - \bar{\Delta}.$$

The neighborhood is therefore characterized by :

$$\|x - \hat{x}\| \leq \min(\check{r}, \hat{r})$$

with

$$\check{r} := \frac{1 - \nu}{(L + L') \bar{\lambda}} - \bar{\Delta}.$$

This is actually true for any norm.

The neighborhood is therefore characterized by :

$$\|x - \hat{x}\| \leq \min(\check{r}, \hat{r})$$

with

$$\check{r} := \frac{1 - \nu}{(L + L') \bar{\lambda}} - \bar{\Delta}.$$

This is actually true for any norm.

Since we prefer a  $P$ -ellipsoids, all the bounds on the right side should be with the  $P$ -norm :

The neighborhood is therefore characterized by :

$$\|x - \hat{x}\| \leq \min(\check{r}, \hat{r})$$

with

$$\check{r} := \frac{1 - \nu}{(L + L') \bar{\lambda}} - \bar{\Delta}.$$

This is actually true for any norm.

Since we prefer a  $P$ -ellipsoids, all the bounds on the right side should be with the  $P$ -norm :

- ▶  $\mathcal{N}' \longrightarrow$  ok (evaluate the Lipschitz constants on the hull  $[x]$ )

The neighborhood is therefore characterized by :

$$\|x - \hat{x}\| \leq \min(\check{r}, \hat{r})$$

with

$$\check{r} := \frac{1 - \nu}{(L + L') \bar{\lambda}} - \bar{\Delta}.$$

This is actually true for any norm.

Since we prefer a  $P$ -ellipsoids, all the bounds on the right side should be with the  $P$ -norm :

- ▶  $\mathcal{N}' \longrightarrow$  ok (evaluate the Lipschitz constants on the hull  $[x]$ )
- ▶  $\bar{\Delta} \longrightarrow$  ok

The neighborhood is therefore characterized by :

$$\|x - \hat{x}\| \leq \min(\check{r}, \hat{r})$$

with

$$\check{r} := \frac{1 - \nu}{(L + L') \bar{\lambda}} - \bar{\Delta}.$$

This is actually true for any norm.

Since we prefer a  $P$ -ellipsoids, all the bounds on the right side should be with the  $P$ -norm :

- ▶  $\mathcal{N}' \rightarrow$  ok (evaluate the Lipschitz constants on the hull  $[x]$ )
- ▶  $\bar{\Delta} \rightarrow$  ok
- ▶  $\nu \rightarrow$  from  $(Q([x^*]) + I) +$  norm equivalence

The neighborhood is therefore characterized by :

$$\|x - \hat{x}\| \leq \min(\check{r}, \hat{r})$$

with

$$\check{r} := \frac{1 - \nu}{(L + L') \bar{\lambda}} - \bar{\Delta}.$$

This is actually true for any norm.

Since we prefer a  $P$ -ellipsoids, all the bounds on the right side should be with the  $P$ -norm :

- ▶  $\mathcal{N}' \rightarrow$  ok (evaluate the Lipschitz constants on the hull  $[x]$ )
- ▶  $\bar{\Delta} \rightarrow$  ok
- ▶  $\nu \rightarrow$  from  $(Q([x^*]) + I) +$  norm equivalence
- ▶  $L$  and  $L' \rightarrow$  from  $\frac{\partial^2 f_i}{\partial x_j \partial x_k}([x]) +$  norm equivalence

The neighborhood is therefore characterized by :

$$\|x - \hat{x}\| \leq \min(\check{r}, \hat{r})$$

with

$$\check{r} := \frac{1 - \nu}{(L + L') \bar{\lambda}} - \bar{\Delta}.$$

This is actually true for any norm.

Since we prefer a  $P$ -ellipsoids, all the bounds on the right side should be with the  $P$ -norm :

- ▶  $\mathcal{N}' \rightarrow$  ok (evaluate the Lipschitz constants on the hull  $[x]$ )
- ▶  $\bar{\Delta} \rightarrow$  ok
- ▶  $\nu \rightarrow$  from  $(Q([x^*]) + I)$  + norm equivalence
- ▶  $L$  and  $L' \rightarrow$  from  $\frac{\partial^2 f_i}{\partial x_j \partial x_k}([x])$  + norm equivalence
- ▶  $P \rightarrow$  from a direct formula